Visual SLAM Based UAV in GPS-denied Environments
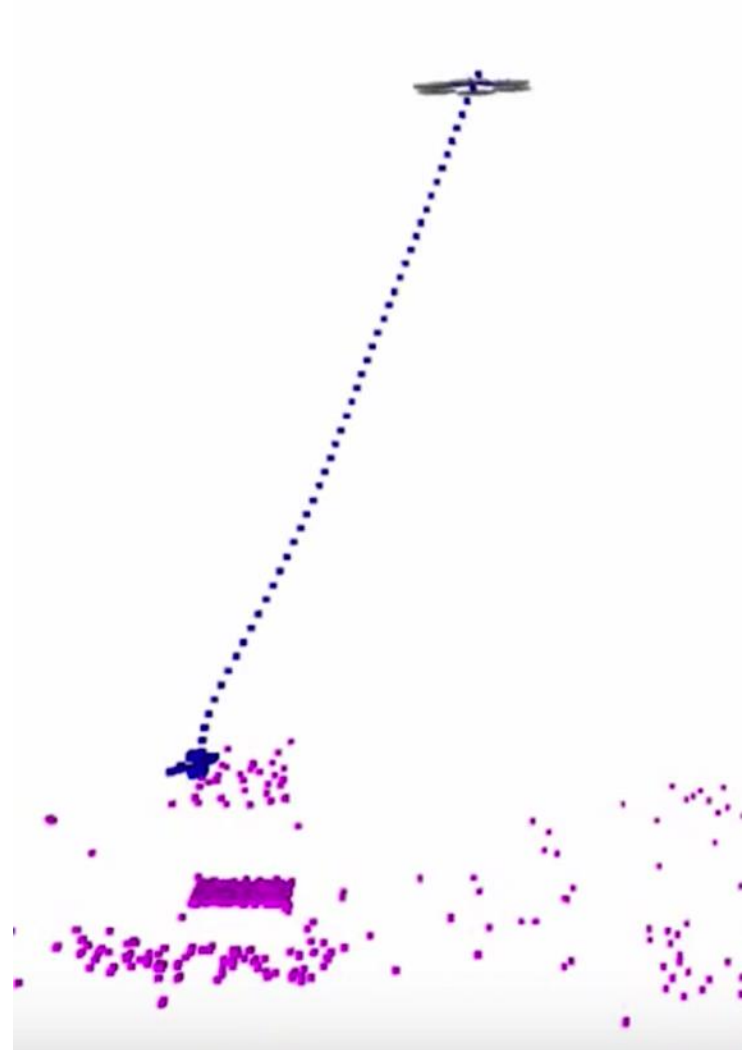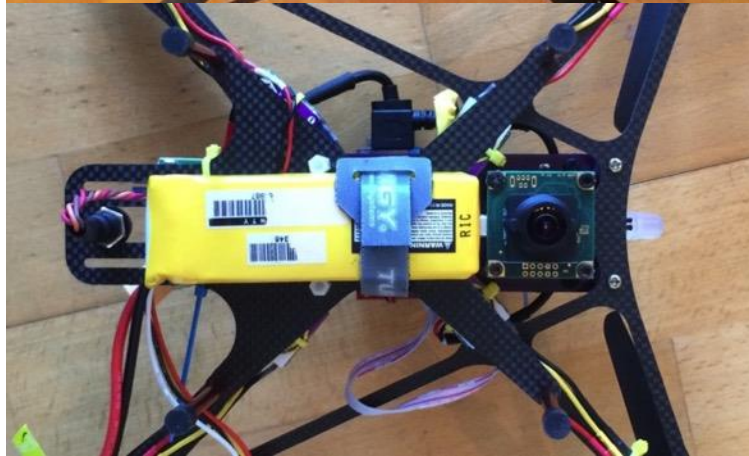
Chang Liu

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Onboard Monocular Visual SLAM

Onboard Visual-inertial Sensor Fusion